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Solving a Class of N-Order Linear Differential Equations by the Recursive Relations and it's Algorithms in MATLAB

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ABSTRACT: In many applied sciences, we find differential equations, which these equations are N-Order Linear differential equations and solutions relatively complex, therefore researchers have forced to use numerical methods, which are contained several errors, i.e. In analysis of computer algorithms, notably in analysis of quicksort and search trees; a number of physics and engineering applications, such as when solving Laplace's equation in polar coordinates; and many other sciences. In this paper, we are using variable change method for the analytic solution a class of N-Order Linear differential equations in problem. Applying a variable change in the equation, then we get conditions where if an equation is also conditions, a simple analytical solution is obtained for it. Because this solution, an exact analytical solution can provide to us, we benefited from the solution of numerical linear differential equations.

Keywords: Ordinary Differential Equation, Self-Adjoint Equation, Linear Differential Equations, Wronskian, MATLAB.

INTRODUCTION

In many applied sciences, we find differential equations, which these equations are N-Order Linear differential equations and solutions relatively complex, therefore researchers have forced to use numerical methods, which are contained several errors. (Mohyud-Din, 2009; Allame, 2011; Borhanifar et al., 2011; Sweilam, 2011; Gülsu et al., 2011; Mohyud-Din et al., 2011; Raftari, 2010 and Gondal et al., 2011).

There are several methods for solving equations, there one of which can be seen in the literature (Qiusheng et al., 1996-1994; Demir et al., 2011; Arfken, 1985; Gandarias, 2011; Batiha et al., 2011 and Ugurlu et al., 2011), where the change of variables is very complicated to use.

In this paper, for solving analytical a class of N-Order Linear differential equations, applying a variable change in the equation, then we get conditions where if an equation is also conditions, a simple analytical solution is obtained for it.

Before going to the main point, we start to introduce two following items:

N-Order Liner Ordinary Differential Equation

Homogeneous linear Ordinary differential equation (ODE) of order n is:

$$y^{(n)} + p_{n-1}(x)y^{(n-1)} + \dots + p_1(x)y' + p_0(x)y = 0$$
(1)

where $p_{n-1}(x), \dots, p_1(x), p_0(x)$ continues functions on (a,b) and $p_{n-1}(x)$ is n-1 times differentiable on (a,b). Equation (1) may be written symbolically as:

$$L(y) = \left\{ D^{n} + p_{n-1}D^{n-1} + \dots + p_{1}D + p_{0} \right\} y = 0$$

The expression

$$L \equiv D^{n} + p_{n-1}D^{n-1} + \dots + p_{1}D + p_{0}$$

is known as a linear differential operator of order n.

Wronskian

The Wronskian of two functions f and g is (Hilderbrand, 1976; Javadpour, 1993 and O'Neil, 1987): W(x) = W(f,g) = f'g - fg'

More generally, for n real- or complex-valued functions $f_1, f_2, ..., f_n$, which are n – 1 times differentiable on (a,b), the Wronskian $W(x) = W(f_1, \dots, f_n)$ as a function on (a,b) is defined by

 f_1 $W(x) = \begin{vmatrix} f_1 & \cdots & f_n \\ \vdots & \ddots & \vdots \\ f_1^{(n-1)} & \cdots & f_n^{(n-1)} \end{vmatrix}$

That is, it is the determinant of the matrix constructed by placing the functions in the first row, the first derivative of each function in the second row, and so on through the (n - 1)st derivative, thus forming a square matrix sometimes called a fundamental matrix.

When the functions f_i are solutions of a linear differential equation, the Wronskian can be found explicitly using Abel's identity, even if the functions f_i are not known explicitly.

Theorem 1: if P(x)y'' + Q(x)y' + R(x)y = 0 then $W(x) = e^{-\int \frac{Q}{P} dx}$

Proof: let two solution of equation by y_1 and y_2 , then, since these solutions satisfy the equation, we have $Py_1'' + Qy_1' + Ry_1 = 0$

 $Py_2'' + Qy_2' + Ry_2 = 0$

Multiplying the first equation by y_2 , the second by y_1 , and subtracting we find $P.(y_1y_2'' - y_2y_1'') + Q.(y_1y_2' - y_2y_1') = 0$

Since Wronskian is given by $W = y_1 y'_2 - y_2 y'$ thus $P \cdot \frac{dW}{dx} + Q \cdot W = 0$ Solving, we obtain an important state. Solving, we obtain an important relation known as Abel's identity, given by

$$W(x) = e^{-\int \frac{Q}{P} dx} .\blacksquare$$

In general case, for N-Order Liner Ordinary Differential Equation (1), we obtain $W(x) = e^{-\int p_{n-1}dx}$

SOLVING A CLASS OF N-ORDER LINEAR DIFFERENTIAL EQUATIONS

Theorem2(Main Theorem): If, a homogeneous linear ordinary differential equation of order ⁿ:

 $y^{(n)} + p_{n-1}(x)y^{(n-1)} + \dots + p_1(x)y' + p_0(x)y = 0$

verify in the conditions:

$$p_{n-k} = \frac{(n-k+1)}{k.n} \left(np'_{n-k+1} + p_{n-1}p_{n-k+1} \right)$$

where $k = 2,3,...,n$

Then, the answer to equation will be

$$y(x) = e^{-\frac{1}{n}\int p_{n-1}dx} \left(C_{n-1}x^{n-1} + \dots + C_1x^1 + C_0 \right)$$

Proof: we show that linear Ordinary differential equation (1) is changeable to two linear differential equations. By replacing of change variable

$$y = u(x).v(x)$$

in equation (1), where u(x) and v(x) are continuous and differentiable functions, and

(4)

(3)

$$\begin{aligned} y &= u.v \\ y' &= u'.v + u.v' \\ y'' &= u''.v + 2u'.v' + u.v' \\ \vdots \\ y^{(n)} &= \sum_{k=0}^{n} \binom{n}{k} u^{(n-k)}.v^{(k)} \\ \text{After placing in equation (1), we have:} \\ \binom{n}{0} v^{(n)} &+ \binom{n}{k} v' u^{(n-1)} + \binom{n}{2} v' u^{(n-2)} + \binom{n}{3} v'' u^{(n-3)} + \ldots + \binom{n}{n-1} v^{(n-1)} u' + \binom{n}{n} v^{(n)} u \\ &+ p_{n-1} \binom{n-1}{k} v^{(n-1)} + \binom{n-1}{n-1} v^{(n-2)} + \binom{n-1}{2} v''^{(n-3)} + \ldots + \binom{n-1}{n-2} v^{(n-2)} u' + \binom{n-1}{n-1} v^{(n-1)} u \\ &+ p_{n-2} \binom{n-2}{0} v^{(n-2)} + \binom{n-2}{1-1} v' u^{(n-3)} + \ldots + \binom{n-2}{n-1} v^{(n-1)} u' + \binom{n-2}{n-2} v^{(n-2)} u \\ &\vdots \\ &+ p_{2} \binom{n-2}{0} v^{(n-2)} + \binom{n-2}{1-1} v' u^{(n-2)} + \ldots + \binom{n-2}{n-1} v^{(n-1)} u' + \binom{n-2}{n-2} v^{(n-2)} u \\ &\vdots \\ &+ p_{2} \binom{n-2}{0} v^{(n-2)} + \binom{n-2}{1-1} v' u' + \binom{2}{2} v'' u \\ &+ p_{1} \binom{n}{0} v^{(n)} + \binom{n-1}{1} v' + p_{n-2} \binom{n-2}{0} v' u^{(n-2)} + \\ &\binom{n}{1} v' + p_{n-1} \binom{n-1}{1-1} v' + p_{n-2} \binom{n-2}{0} v' u^{(n-2)} + \\ &\binom{n}{1} \binom{n-1}{1} v' + p_{n-2} \binom{n-2}{1-2} v' + p_{n-3} \binom{n-3}{0} v' u^{(n-3)} + \\ &\vdots \\ &\binom{n}{n} v^{(n)} + p_{n-1} \binom{n-1}{n-1} v^{(n-1)} + p_{n-2} \binom{n-2}{n-2} v^{(n-2)} + \cdots + p_{1} \binom{1}{1} v' + p_{0} v u \\ &= 0 \\ \text{Or} \\ &v u^{(n)} + \sum_{k=1}^{n} \left[\sum_{i=0}^{k} \binom{n+i}{k-i} p_{n-i} v^{(k-i)} \right] u^{(n-k)} = 0 \\ \text{Where } P_{n} (x) = 1. \end{aligned}$$

$$\Rightarrow v' = -\frac{1}{n} p_{n-1} v$$
$$\Rightarrow v = e^{-\frac{1}{n} \int p_{n-1} dx}$$
(6)

Now, corresponding to equation (3) we have $\frac{1}{1}$

$$v(x) = e^{-\frac{1}{n} \int p_{n-1} dx} = \sqrt[n]{W(x)}$$
(7)

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(5)

Now, using Equation (5), (7) and assuming that the coefficients $u^{(n-2)}, u^{(n-3)}, ..., u', u$ are zero, we get the condition that if an equation is also conditions, can be solved with this method: (n-1)(n-2)(n)~

$$\begin{aligned} & \begin{pmatrix} n \\ 2 \end{pmatrix} p^{*} + p_{n-1} \begin{pmatrix} n \\ 1 \end{pmatrix} p^{*} + p_{n-2} \begin{pmatrix} n \\ 0 \end{pmatrix} p^{*} = 0 \\ \Rightarrow \left(-\frac{n-1}{2n} p_{n-1}^{2} - \frac{n-1}{2} p_{n-1}' + p_{n-2} \right) v = 0 \\ \hline p_{n-2} &= \frac{(n-1)}{2!.n} (np_{n-1}' + p_{n-1}^{2}) \\ And \\ & \begin{pmatrix} n \\ 3 \end{pmatrix} v''' + p_{n-1} \begin{pmatrix} n-1 \\ 2 \end{pmatrix} v'' + p_{n-2} \begin{pmatrix} n-2 \\ 1 \end{pmatrix} v' + p_{n-3} \begin{pmatrix} n-3 \\ 0 \end{pmatrix} v = 0 \\ \hline p_{n-3} &= \frac{(n-1)(n-2)}{3!.n^{2}} (n^{2} p_{n-1}'' + 3np_{n-1} p_{n-1}' + p_{n-1}^{3}) \\ And \\ \hline p_{n-4} &= \frac{(n-1)(n-2)(n-3)(n^{2} p_{n-1}'' + 3np_{n-1} p_{n-1}' + 6np_{n-1}^{2} p_{n-1}' + 6np_{n-1}^{2} p_{n-1}' + 6np_{n-1}^{2} p_{n-1}' + p_{n-1}^{4}) \\ In general, we can obtain the following recursive relation: \\ \hline p_{n-k} &= \frac{(n-k+1)}{k.n} (np_{n-k+1}' + p_{n-1} p_{n-k+1}) \\ Where k = 2, 3, ..., n \end{aligned}$$
(8)

vvnere

✓ So if a linear differential equation in Equation (10) and the above assumptions is true, according to equation (5) we have:

$$v \mathcal{U}^{(n)} = 0 \qquad \Rightarrow \quad \mathcal{U}^{(n)} = 0$$

Or
$$\mathcal{U}(x) = C_{n-1} x^{n-1} + \dots + C_1 x^1 + C_0 \qquad (11)$$

Where C_{n-1}, \dots, C_1, C_0 are arbitrary real numbers. So, we have from Equations (4), (7) and (11):

$$v(x) = e^{-\frac{1}{n}\int p_{n-1}dx} = \sqrt[n]{W(x)}$$

$$u(x) = C_{n-1}x^{n-1} + \dots + C_1x^1 + C_0$$
(12)

And, the answer to linear differential equation (1) will be

$$y(x) = v(x)u(x) = e^{-\frac{1}{n}\int p_{n-1}dx} \left(C_{n-1}x^{n-1} + \dots + C_1x^1 + C_0 \right)$$
(13)

EXAMPLES and APPLICATIONS

EX.1) Solve the equation

$$(1-x^2)y'' - 2xy' - \frac{1}{1-x^2}y = 0$$

Solution: By virtue of equation (1) we have

$$p_1(x) = \frac{-2x}{1-x^2}$$
, $p_0(x) = \frac{-1}{(1-x^2)^2}$

Obviously, that equation (8) is established, i.e.

$$p_0 = \frac{(2-1)}{2!.2} \left(2p_1' + p_1^2 \right)$$

So, we have:

(14)

$$v(x) = e^{-\frac{1}{2}\int p_{l}dx} = e^{-\frac{1}{2}\int \frac{-2x}{1-x^{2}}dx} = e^{-\frac{1}{2}Ln(1-x^{2})} = \frac{1}{\sqrt{1-x^{2}}}$$

 $\mathcal{U}(\mathbf{X}) = C_1 \mathbf{X} + C_0$

And, the answer to linear differential equation (14) will be

$$y(x) = v(x)u(x) = \frac{1}{\sqrt{1-x^2}} (C_1 x + C_0)$$

Analytical and very simple answer is obtained, while using the series, is a long way.

EX.2) Solve the equation

$$y''' + xy'' + \frac{3+x^2}{3}y' + \frac{9x+x^3}{27}y = 0$$

Solution: By virtue of equation (1) we have

$$p_2(x) = x$$
, $p_1(x) = \frac{3 + x^2}{3}$, $p_0(x) = \frac{9x + x^3}{27}$

Obviously, that equations (8) and (9) are established, i.e.

$$p_{1} = \frac{(3-1)}{2!.3} (3p'_{1} + p_{1}^{2})$$
$$p_{0} = \frac{(3-1)(3-2)}{3!.3^{2}} (3^{2} p''_{2} + 3.3.p_{2} p'_{n-1} + p_{2}^{3})$$

So, we have:

$$v(x) = e^{-\frac{1}{3}\int p_2 dx} = e^{-\frac{1}{3}\int x dx} = e^{-\frac{1}{6}x^2}$$

$$\mathcal{U}(X) = C_2 x^2 + C_1 x^1 + C_0$$

And, the answer to linear differential equation (15) will be

$$y(x) = v(x)u(x) = e^{-\frac{1}{6}x^{2}} \left(C_{2}x^{2} + C_{1}x + C_{0} \right)$$

Analytical and very simple answer is obtained, while using the series, is a long way.

EX.3) Solve the equation

$$e^{-x}y'' + y' + \frac{2 + e^x}{4}y = 0$$

Solution: By virtue of equation (1) we have

$$p_1(x) = e^x$$
, $p_0(x) = \frac{e^x(2+e^x)}{4}$

Obviously, that equation (8) is established, i.e.

$$p_0 = \frac{(2-1)}{2!.2} \left(2p_1' + p_1^2 \right)$$

So, we have:

$$v(x) = e^{-\frac{1}{2}\int p_1 dx} = e^{-\frac{1}{2}\int e^x dx} = e^{-\frac{1}{2}e^x}$$

 $u(x) = C_1 x^1 + C_0$

And, the answer to linear differential equation (16) will be

$$y(x) = v(x)u(x) = e^{-\frac{1}{2}e^{x}}(C_{1}x + C_{0})$$

Analytical and very simple answer is obtained, while using the series, is a long way.

EX.4) Solve the equation

$$\frac{d}{dx}(\alpha .x^{n}y') + \frac{\alpha .n.(n-2)}{4}x^{n-2}y = 0$$
(17)

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(15)

(16)

Where α , *n* are constants and $\alpha \neq 0$ [4, 5 and 6]. **Solution:** By virtue of equation (1) we have $p_1(x) = \frac{n}{x}$, $p_0(x) = \frac{n(n-2)}{4x^2}$ Obviously, that equation (8) is established, i.e. $p_0 = \frac{(2-1)}{2!.2} (2p'_1 + p_1^2)$ So, we have: $v(x) = e^{-\frac{1}{2}\int p_1 dx} = e^{-\frac{n}{2}Ln(x)} = x^{-\frac{n}{2}}$ $u(x) = C_1 x^1 + C_0$

And, the answer to linear differential equation (17) will be

$$y(x) = v(x)u(x) = x^{-\frac{1}{2}}(C_1x + C_2)$$

Analytical and very simple answer is obtained, while using the series, is a long way.

v'' + 2v' + v = 0

Solution: By virtue of equation (1) we have

$$p_1(x) = 2$$
 , $p_0(x) = 1$

Obviously, that equation (8) is established, and we have:

 $v(x) = e^{-\frac{1}{2}\int p_1 dx} = e^{-\frac{1}{2}\int 2dx} = e^{-x}$, $u(x) = C_1 x + C_0$

And, the answer to linear differential equation (18) will be

$$y(x) = v(x)u(x) = e^{-x}(C_1x + C_0)$$

Analytical and very simple answer is obtained.

EX.6) In the special case, if $p_{n-1}(x) = 1$, then we have

$$p_{n-k} = \frac{(n-k+1)}{k.n} (p_{n-k+1}) = \binom{n}{k} \frac{1}{n^k}$$

where k = 2, 3, ..., n.

And, the answer to linear differential equation (1) will be

$$y(x) = e^{\frac{1}{n}x} \left(C_{n-1}x^{n-1} + \dots + C_1x^1 + C_0 \right).$$

ALGORITHMS IN MATLAB Algorithm for Finding the Functions

Algorithm for finding the functions in equation (10) are true, is as follows:

First, in MATLAB \Rightarrow Menu "File" \Rightarrow Select "NEW" \Rightarrow Select "M-File" \Rightarrow The following function to copy in file, and then save the file to "norder_find.m" name: *function norder_find(f)* syms n k n=f{2}; for k=2:n $f\{k\}=(((n-k+1)/(n^*k))^*((n^*diff(f\{k-1\}))+(f\{1\}^*f\{k-1\})));$ disp(sprintf('p(%d)', n-k)); $display(simplify(f\{k\}));$ end

end

Secondly, in the window "Command Windows" of MATLAB, type the following commands:

(18)

>> syms x
>> f{1} = "function: p_{n-1}(x)";
>> f{2} = "order differential equation: n";
>> norder_find(f)

EX.7) in the window "Command Windows" of MATLAB, type the following commands:

>> syms x >> f{1} = x^2; >> f{2} =2; >> norder_find(f)

Then, key "ENTER" p(0)= $x+1/4^*x^4$

Thus, functions that are true in the equation (10), are calculated, the desired equation is as follows:

$$y'' + x^{2}y' + \frac{4x + x^{4}}{4}y = 0$$

i.e.
$$y(x) = e^{-\frac{1}{6}x^{3}} (C_{1}x + C_{0}).$$

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Algorithm to check the true functions Algorithm to check the true functions in equation (10), is as follows:

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Algorithm to check the true functions in equation (10), is as follows:

First, in MATLAB \Rightarrow Menu "File" \Rightarrow Select "NEW" \Rightarrow Select "M-File" \Rightarrow The following function to copy in file, and then save the file to "norder_test.m" name:

function norder_test(f)

syms n k

n=size(f,2);
```

```
k=2;
flag=1;
while(flag==1 && k < = n)
     if (simplify(f{n-k+1}-(((n-k+1)/(n*k))*((n*diff(f{n-k+2}))
                       +(f{n}*f{n-k+2})))==0)
       flag=1;
       k=k+1;
     else
       flag=0;
     end
end
if (flag==1)
  display('Yes');
else
  display('No');
end
end
```

Secondly, in the window "Command Windows" of MATLAB, type the following commands: >> syms x >> f{1}="the intended function : $p_0(x)$ "; >> f{2}="the intended function : $p_1(x)$ "; >>... >> $f{n}="the intended function : p_{n-1}(x)";$ >> norder test(f)

EX.8) in the window "Command Windows" of MATLAB, type the following commands: >> svms x >> $f{1}=1/2 \exp(x)+1/4 \exp(2x);$ >> $f{2}=exp(x);$ >> norder test(f)

Then, key "ENTER" >> yes

 $p_1(x) = e^x , \quad p_0(x) = \frac{1}{2}e^x + \frac{1}{4}e^{2x},$ equation (10) are established, i.e. equation $y'' + e^x y' + (\frac{1}{2}e^x + \frac{1}{4}e^{2x})y = 0$

is the answer to:

$$y(x) = e^{-\frac{1}{2}e^{x}} (C_1 x + C_0)$$

CONCULSION

The governing equation for stability analysis of a variable cross-section bar subject to variably distributed axial loads, dynamic analysis of multi-storey building, tall building and other systems are written in the form of a unified linear differential equation of the second order.

The key step in transforming the unified equation is the equation (10).

Many difficult problems in the field of static and dynamic mechanics are solved by the unified equation proposed in this paper.

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